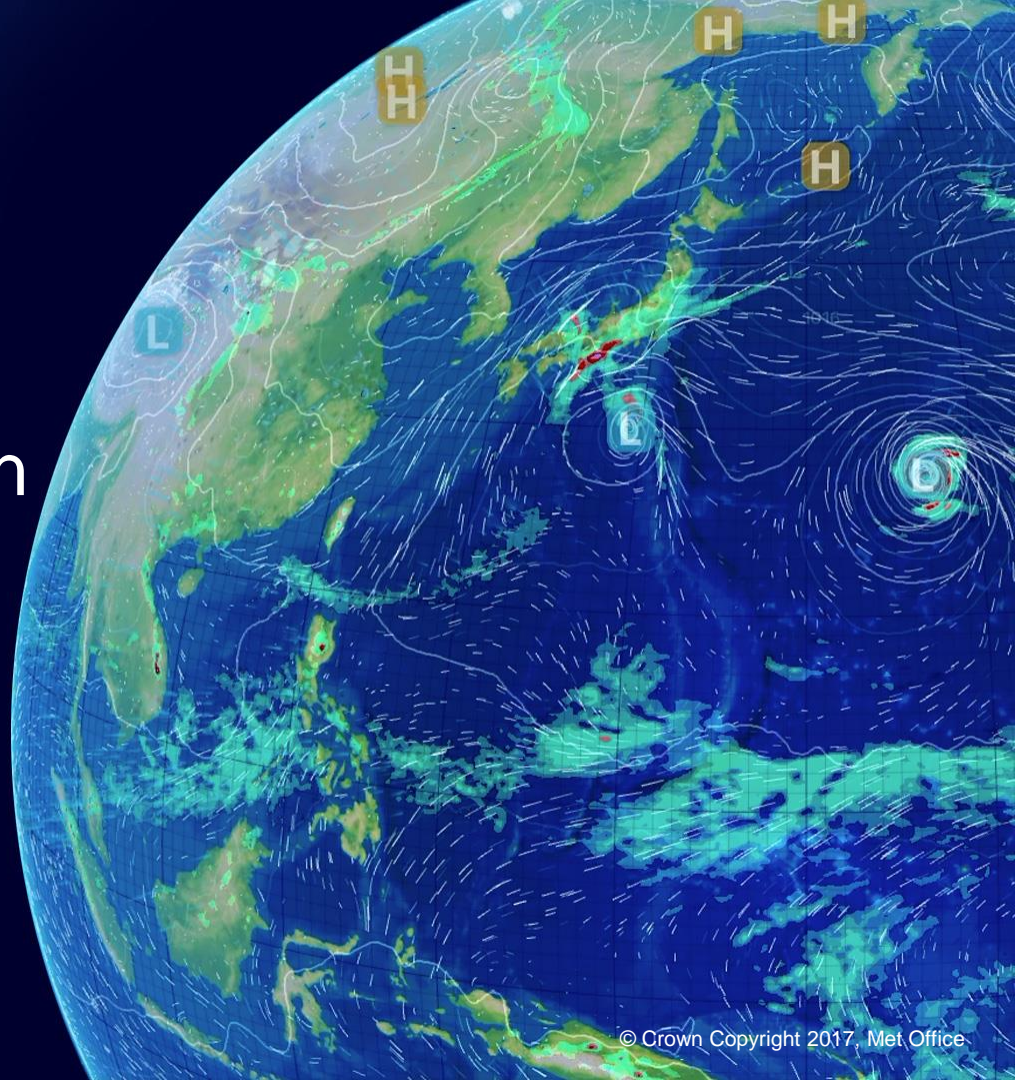


# Doppler radial wind spatially correlated observation error: operational implementation and initial results

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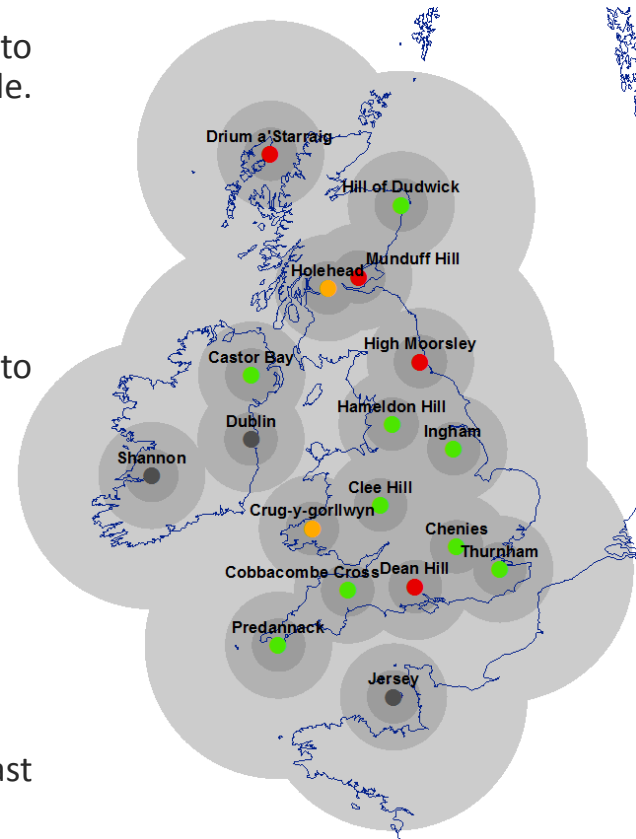
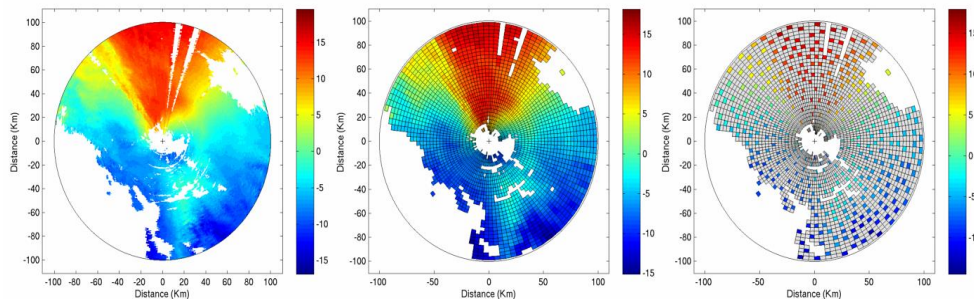


## Motivation

Convective-scale NWP requires a high resolution data assimilation system to provide initial conditions containing information at the appropriate scale. Therefore we require observations that have:

- High resolution
- High repetition time
- Large coverage

Currently observations with these properties are ‘Superobbed’ or thinned to remove correlated error.



Using correlated observation error statistics can improve assimilation and forecast performance. It also allows the use of observations at the appropriate scale.

## Diagnosing observation error statistics

We have studied the *Desroziers et al. (2005)* Diagnostic (*Waller et al., 2016a, 2017*) and used it to estimate errors for:

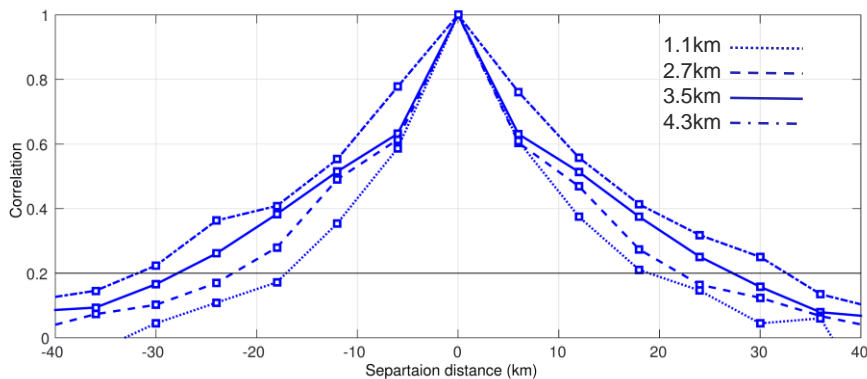
- Doppler radar radial winds (*Waller et al., 2016b*).
- SEVIRI observations (*Waller et al. 2016c*).
- Atmospheric motion vectors (*Cordoba et al. 2017*).

$$R \approx E[d_a^o d_b^{oT}]$$

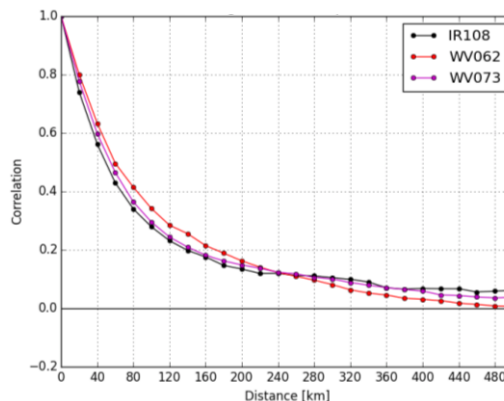
**Background residual:**  $d_b^o = y - H(x^b)$

**Analysis residual:**  $d_a^o = y - H(x^a)$

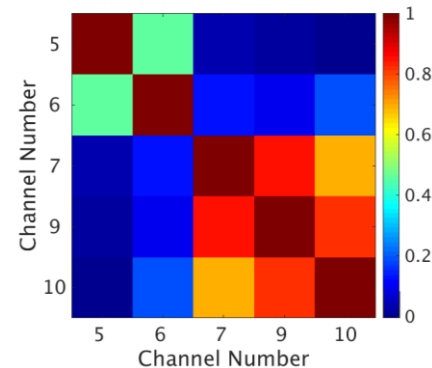
We can now use more of these observations.



Spatial radar error correlations for elevation 2° for different heights.



Spatial AMV error correlations



Inter-channel SEVIRI error correlations

# Implementation

## Implementation - Parallelisation

### Traditional Parallelisation

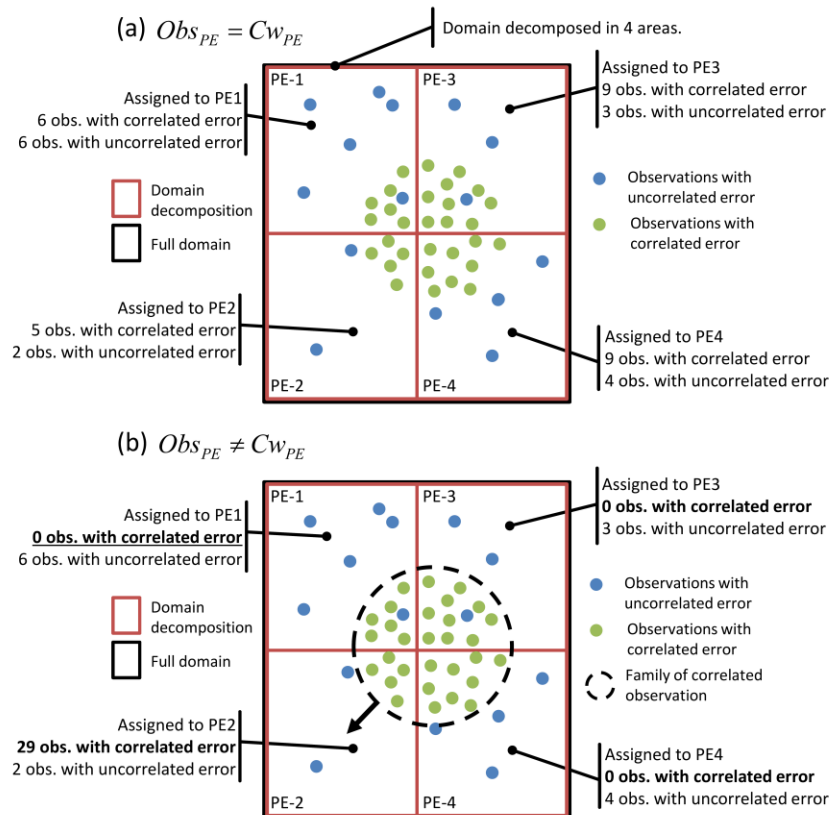
- One model column ( $Cw$ ) per observation ( $Obs$ )
- Each  $Obs$  and  $Cw$  are distributed across the PE using a domain decomposition  $\rightarrow Obs_{PE} = Cw_{PE}$

### New Parallelisation

- Each  $Cw$  are distributed across the PE using a domain decomposition.
- Each  $Obs$  are distributed across the PE using a family decomposition  
 $\rightarrow Obs_{PE} \neq Cw_{PE}$

### Family

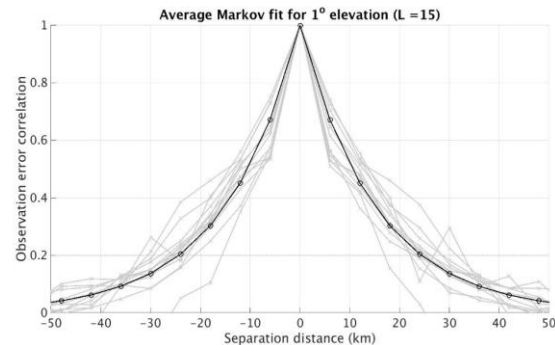
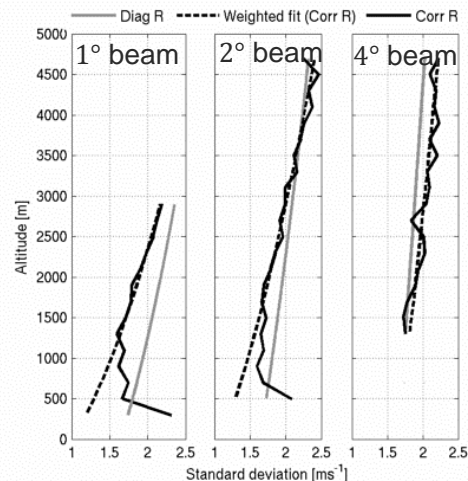
- A family is a group of observations that are correlated.
- Each observation is assigned to a family.



## Implementation - R

The observation error covariance matrix ( $R_s = DCD$ ) is derived on the fly and the observation penalty can be calculated as follows:

1. Determine  $R_s = DCD$ , where  $C_{i,j} = \exp\left(\frac{-|\Delta y_{i,j}|}{L_r}\right)$  and  $\Delta y_{i,j}$  is the distance between each pair of observations in the family.
2. Calculate a vector of model minus observation differences  $d_o^b = (y - H(x))$
3. Calculate the sensitivity  $Q = R_s^{-1}(y - H(x))$  using a Cholesky decomposition.
4. The total observation penalty is calculated:
 
$$J_o = (y - H(x))^T R_s^{-1} (y - H(x))$$



# Initial results: Analysis

## Results – VAR statistics

Trials

UKV PS37 (3 hourly – 3DVAR)

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Three experiments run for 20 days  
from the 1<sup>st</sup> April 2016

- 6km thinning with Diagonal R  
→ **Control** (~2000 rad obs. per cycle)
- 6km thinning with Correlated R  
→ **Corr-R-6km** (~2000 rad obs. per cycle)
- 3km thinning with Correlated R  
→ **Corr-R-3km** (~8000 rad obs. per cycle)

System performance

There is no significant difference in iteration count and running time.

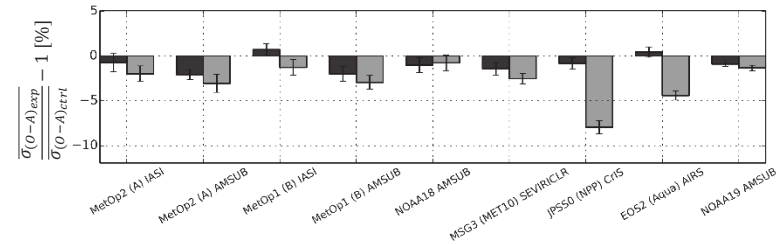
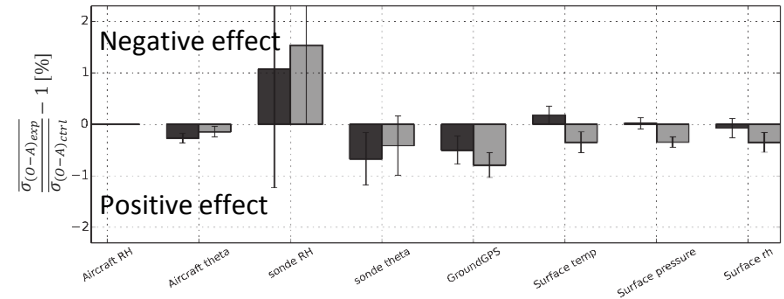
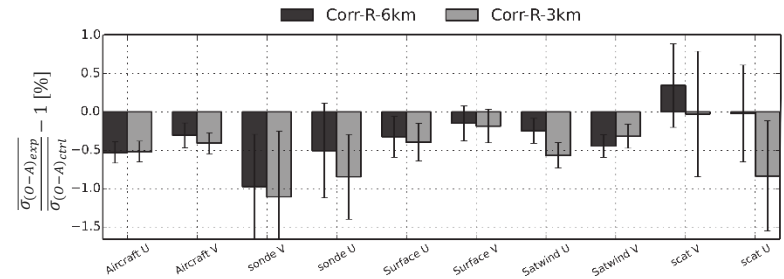
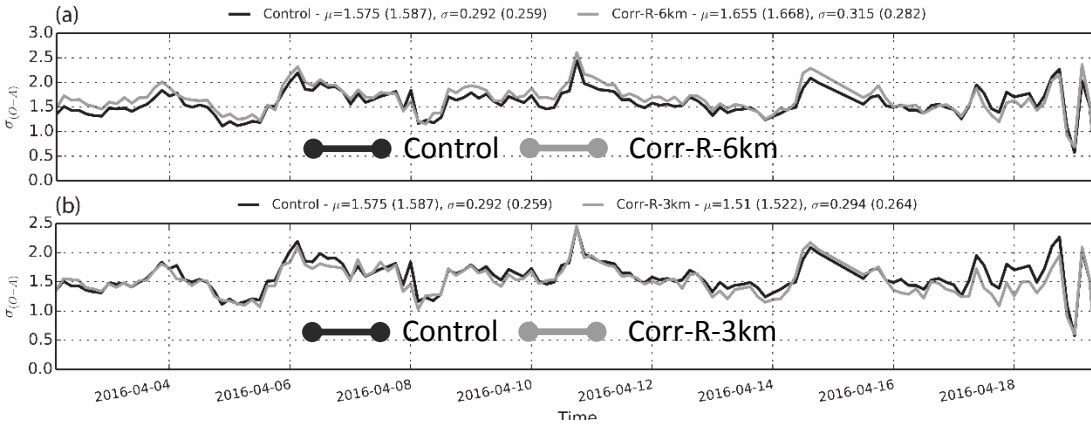
Effect on Penalty:

(Compare to the control)

- The **Corr-R-6km** has a smaller background penalty and a larger observation penalty.  
  
→ Correlated R reduces the weight of the observations.



## Results – VAR statistics 1/2



### Effect on $O - A$ statistics

Introduction of correlated R reduces the fit to Doppler observations.

Increasing the observation density shows similar  $O - A$  statistics to the control.

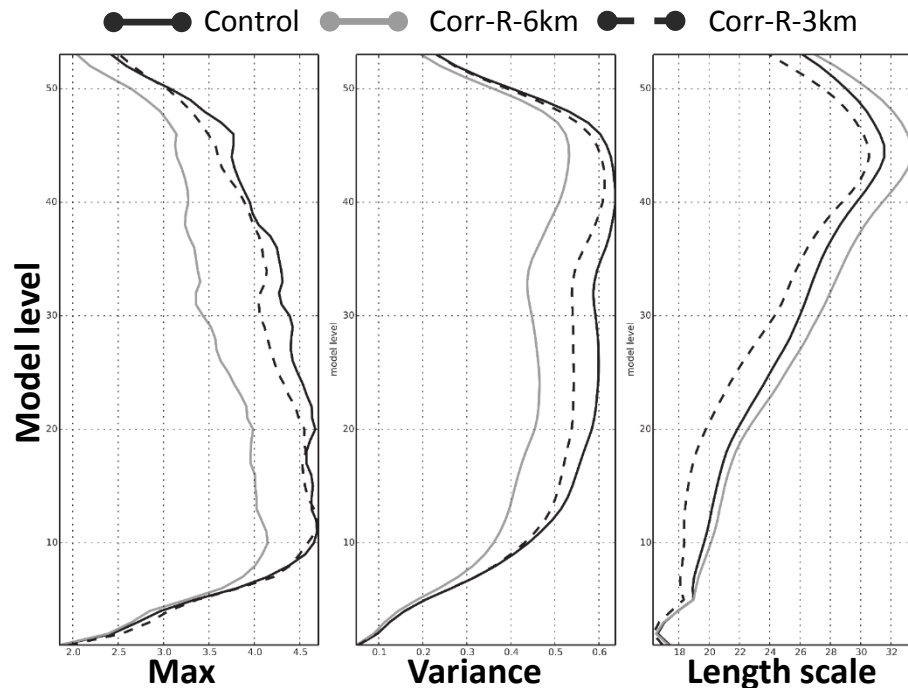
Most observations show a **small benefit** from the introduction of the correlated error.

## Results – VAR statistics 2/2

Effect on wind increments:

(Compared to the control)

- The **Corr-R-6km** wind's increments are smoother with smaller range.
- The **Corr-R-3km** wind increments show more small scale features with smaller range (bigger than Corr-R-6km).



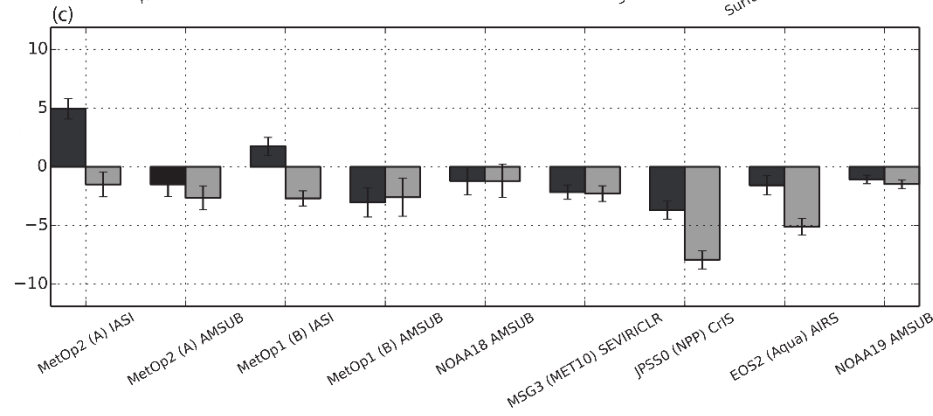
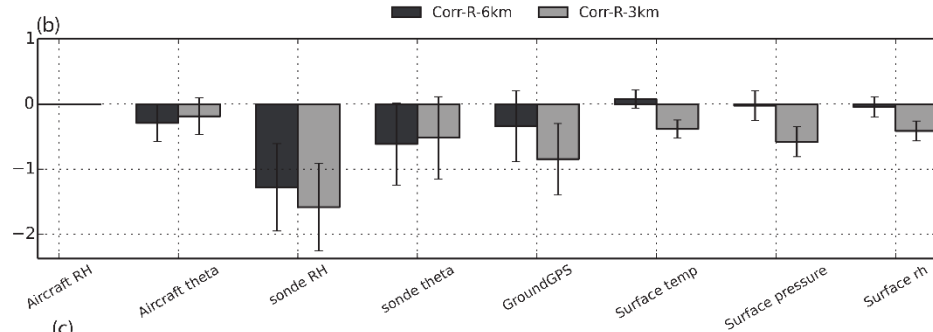
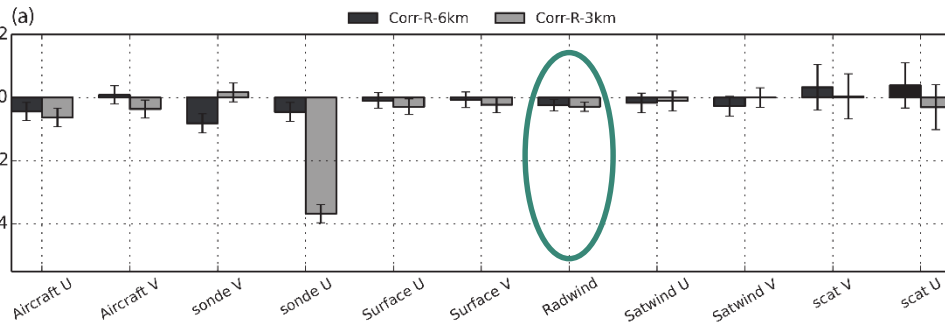
# Initial results: Forecast

## Results – Impact on forecast 1/2

### Effect on $O - B$

Most observations show a **small benefit** from the introduction of the correlated error.

$$\frac{\overline{\overline{\overline{\sigma_{(O-B)exp}}}}}{\overline{\overline{\overline{\sigma_{(O-B)ctrl}}}}} - 1 \text{ [%]}$$



## Results – Impact on forecast 2/2

Surface verification: Weighted Basket of Indices (ETS & RMS scores)

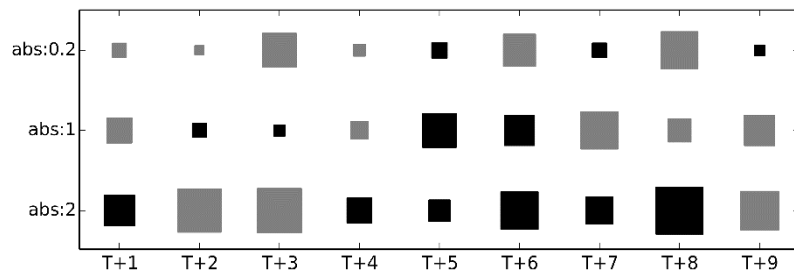
	Corr-R-6km [%]	Corr-R-3km [%]
Vis	+0.027	+0.046
Precip	-0.063	-0.050
Cloud Cover	+0.047	+0.012
Cloud Base Height	-0.013	-0.005
Temp	-0.014	+0.005
Wind	+0.010	+0.013
<b>Overall</b>	<b>-0.005</b>	<b>+0.021</b>

**Very small impact!**

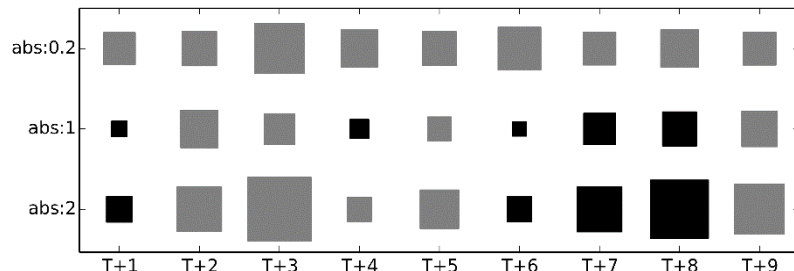
Fraction skill score:

$$\Delta FSS = FSS_{Exp} - FSS_{Ctrl}$$

max  $|\Delta FSS| = 0.009$  [Ctrl: Control, Exp:Corr-R-6km]



max  $|\Delta FSS| = 0.03$  [Ctrl: Control, Exp:Corr-R-3km]



# Conclusion

## Conclusion

- **High resolution NWP requires data assimilation that can assimilate observations at the appropriate spatial and temporal resolution.**
- **Typically observations at these resolutions will have correlated error which should be accounted for.**
- **We have developed parallelisation strategy to account for correlated observation errors in an operational variational data assimilation system.**
- **It has been tested using Doppler radial wind observations.**
  - The system performance is good.
  - Higher resolution observations can be used in the assimilation.
  - Small benefits in the assimilation systems have been seen including the addition of small scale information.
  - The impact on the forecast is neutral.
- **The strategy developed should be applicable to multiple observation types and we plan to assess the impact of correlated observation error for AMV and Radar reflectivity observations.**

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## Thank you. Any Questions?



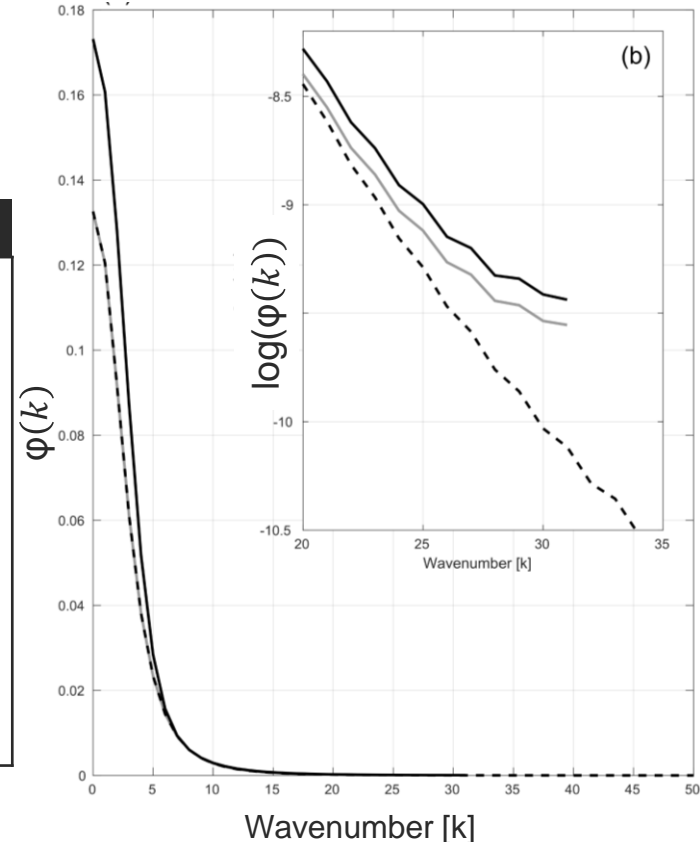
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## Impact on analysis error

Simple model experiment using circulant error covariance matrices and direct observations allows us to analyse impact at different scales in the analysis.

Optimal R	Sub-optimal R
<p>— Corr R (half obs density) <math>\Rightarrow</math> Corr-R-6km</p> <p>- - Corr R (full obs density) <math>\Rightarrow</math> Corr-R-3km</p> <p><u>Corr-R-6km:</u> Analysis error reduced at all scales, but most improvement in large scale.</p> <p><u>Corr-R-3km:</u> Analysis improved at all scales, greater improvement at small scale and additional information at even smaller scales.</p>	<p>— Diag R (half obs. density) <math>\Rightarrow</math> Control</p>



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